Kernel Mean Embedding for Stochastic Optimization and Control

Based on joint work with Moritz Diehl and Bernhard Schölkopf

Jia-Jie Zhu Max Planck Institute for Intelligent Systems Tübingen, Germany

2020/6/10

Optimization under uncertainty



• Chance constraint [Charnes et al. 50s] (downside: intractable)

$$\min_x \; l(x) \quad ext{subject to} \; \operatorname{P} C(x,\xi) \leq 0 \geq 1-lpha$$

• Robust optimization [Ben-Tal et al. 90s] (downside: conservative)

 $\min_x \; l(x) \quad ext{subject to} \; f(x,\xi) \leq 0, \; orall \xi \in \mathcal{U}$

Scenario approach to chance constraint

$$\min_x \ l(x), \quad ext{subject to} \ C(x,\xi_i) \leq 0 ext{ for } i=1,\ldots,N.$$

• This is a convex approximation to the channee-constrained problem

$$\min_x \; l(x), \quad ext{subject to} \; \operatorname{P}(C(x,\xi) \leq 0) \geq 1-lpha.$$

- If $N
 ightarrow \infty$, chance constraint is satisfied at level almost = 1. i.e. conservative
- If N is small, we may be too optimistic

Reducing conservativeness

 $\min_x \ l(x), \quad ext{subject to} \ C(x,\xi_i) \leq 0 ext{ for } i=1,\ldots,N.$

How about we pick a subset of scenarios $\{\xi_i\}_{i=1}^N$ to discard?

Kernel mean embedding

- Recall a kernel is a symmetric, positive semi-definite bivariate function, e.g., $k(x,x') = \exp\left(-rac{1}{2\sigma^2}\|x-x'\|_2^2
 ight)$.
- Kernel mean embedding (KME) maps probability distributions to functions in a Hilbert space.

$$\mu:P\mapsto \int k(x,\cdot)\ dP(x), \quad \hat{\mu}:P\mapsto \sum_{i=1}^N lpha_i k(x_i,\cdot),\ x_i\sim P$$

- μ can be thought of a generalized moment vector

Why use kernel mean embedding for optimization

• It allows us to perform optimization problem in the space of probability distribution.

$$egin{aligned} \min_{P,\mu} & \int l\,dP \ \mathrm{subject \ to} & \|\mu-\mu_{\hat{P}}\|_{\mathcal{H}} \leq \epsilon. \ & \int \phi(x)\,dP(x) = \mu_p. \end{aligned}$$

- By virtue of the RKHS tools, optimization is often tractable.
- It induces a metric on the space of distributions, which can be used for distributionally robust optimization (DRO; cf. Z. 2020).

Illustration of our idea

Use L-1 penalty to discard scenarios while staying close to the original distribution.



Scenario approach with discarding

- Discard the scenarios ξ_i with the index set $\mathcal{I} = \{i \mid lpha_i = 0, i = 1, \dots, n\}$ by solving

$$\min_lpha \ \|\sum_{i=1}^N lpha_i \phi(\xi_i) - \hat{\mu}_\xi \|_\mathcal{H}^2 + \lambda \|w^ op lpha\|_1.$$

• Then, we re-solve the stochastic programming problem with the reducedset scenarios $\mathcal{R}:=\{1,\ldots,n\}\setminus\mathcal{I}.$

Stochastic control example



Discard scenarios



Discard more...



Result: optimistic controller



Result: reduced conservatism



Takeaway

• Kernel mean embedding in RKHS allows efficient optimization in distribution space

```
\min_P f(P) 	ext{ becomes } \min_{\mu_p} f(P).
```

- It can be combined with other methods like DL, e.g., MMD-GAN, adversarial training, blah blah blah.
- This paper focus on reducing conservativeness of the scenario approach to stochastic programming and control. What if we wish to be more robust?
 - Kernel Distributionally Robust Optimizaiton (K-DRO. See the next paper: Z et al., 20.)

Thank you! This talk is based on

- Z, Diehl, Schölkopf, 2020. A Kernel Mean Embedding Approach to Reducing Conservativeness in Stochastic Programming and Control. L4DC
- Z, Jitkrittum, Diehl, Schölkopf, 2020. Kernel Distributionally Robust Optimization. Preprint
- Z, Jitkrittum, Diehl, Schölkopf, 2020. Worst-Case Risk Quantification under Distributional Ambiguity using Kernel Mean Embedding in Moment Problem. Preprint
- Z, Muandet, Diehl, Schölkopf, 2019. A New Distribution-Free Concept for Representing, Comparing and Propagating Uncertainty in Dynamical Systems with Kernel Probabilistic Programming. IFAC 2020